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new computation schemes in problems of linear algebra, differential and integral equations, nonlinear analysis, and so on. The general theory of approximate methods includes many known Page 17/52

fundamental results.

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Physics, Trieste, Italy. ABSTRACT Let E be real Banach space which is both uniformly convex and uniformly smooth. Let T: $D(T) C E \rightarrow E be$ bounded maccretive operator, where the domain of T, Page 22/52

D(T); is a proper subset of E. Equations M A

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Kiev (1976), pp. 61-97. Google Scholar

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Krasnosel . We take as the approximate Echietion of MA equation (1) when y = y5 then vector xq = BZQ. Bince ZO e 05, we have Ma-o i/oll ^ o, (14) i.e. XQ satisfies (8). The approximate solution of Page 31/52

operator equations 203 Theorem 1 The approximate A solution xq is strongly convergent to the exact solution XO: xt-'-xa as 6->-0. (15) Proof.

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strongly nonlinear partial equations. MA

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operator equations with non-unique solutions M A Krasnoselskii (PDF) Convergence of approximate solutions of nonlinear ... approximate solution of a linear operator equation of the Page 38/52

form Au = f, where / is a given element in some suitably A normed linear space and A is either a matrix, an integral, or an abstract operator in this space.

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Iterative Method

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for then Approximate Solution system of S M A equations, an approximate solution converges to the exact one. .. results in accretive operator theory was a relation between the Page 40/52

solution of operator equation. Au = 0, where. A. is.

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uniqueness of periodic solutions for a new system of A differential equations. By employing fixed point theorems for increasing ?-\$(h,\tau)\$-concave operators, we establish the existence of Page 42/52

unique periodic solution for our differential system and then give a monotone iterative scheme to approximate the unique periodic solution.

Existence and uniqueness of periodic
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solutions for a

Operator The operator equations under investigation include various linear and nonlinear types of ordinary and partial differential equations, integral equations, and Page 44/52

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inconsistent (it has no solution) when constructed with random coef ficients. However . an overdetermined system will have solutions in some cases, for example if some equation occurs several times in the system, or Page 47/52

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evolution equations with almost sectorial operators and nonlocaleskii conditions. The existence results are obtained by first defining Green's function and approximate controllability by specifying a Page 49/52

suitable control function.

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